

Two-dimensional adaptive Fourier decomposition

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One-dimensional adaptive Fourier decomposition, abbreviated as 1-D AFD, or AFD, is an adaptive representation of a physically realizable signal into a linear combination of parameterized Szegő and higher-order Szegő kernels of the context. In the present paper, we study multi-dimensional AFDs based on multivariate complex Hardy spaces theory. We proceed with two approaches of which one uses Product-TM Systems; and the other uses Product-Szegő Dictionaries. With the Product-TM Systems approach, we prove that at each selection of a pair of parameters, the maximal energy may be attained, and, accordingly, we prove the convergence. With the Product-Szegő dictionary approach, we show that pure greedy algorithm is applicable. We next introduce a new type of greedy algorithm, called Pre-orthogonal Greedy Algorithm (P-OGA). We prove its convergence and convergence rate estimation, allowing a weak-type version of P-OGA as well. The convergence rate estimation of the proposed P-OGA evidences its advantage over orthogonal greedy algorithm (OGA). In the last part, we analyze P-OGA in depth and introduce the concept P-OGA-Induced Complete Dictionary, abbreviated as Complete Dictionary. We show that with the Complete Dictionary P-OGA is applicable to the Hardy H^2 space on 2-torus. Copyright © 2016 John Wiley & Sons, Ltd.

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1. Preparation

We will give a brief introduction to the related background knowledge as well as the existing one-dimensional adaptive Fourier decomposition (1-D AFD) theory. Denote by \mathbf{D} the unit disc and \mathbf{C} the complex plane. The present paper concentrates in the unit disc context. There is a parallel theory for the upper-half plane context [1, 2]. The space $L^2(\partial\mathbf{D})$ can be expressed as the direct sum of the two relevant boundary Hardy spaces, viz.,

$$L^2(\partial\mathbf{D}) = H^2_+(\partial\mathbf{D}) \oplus H^2_-(\partial\mathbf{D}),$$

where $H^2_+(\partial\mathbf{D})$ and $H^2_-(\partial\mathbf{D})$ consist of, respectively, the non-tangential boundary limits of the complex Hardy H^2 -functions inside and outside the unit disc. The mentioned complex Hardy spaces of holomorphic functions inside and outside the unit disc are, respectively, denoted by $H^2_{\pm}(\mathbf{D})$. The non-tangential boundary limit mappings from $H^2_{\pm}(\mathbf{D})$ to their boundary limit spaces $H^2_{\pm}(\partial\mathbf{D})$ are isometric isomorphisms. The closed subspaces $H^2_{\pm}(\partial\mathbf{D})$ of $L^2(\partial\mathbf{D})$ are, in fact, the collections of the functions of the forms $(f \pm iHf)/2 \pm c_0/2$, $c_0 \in \mathbf{C}$, respectively, where H is the Hilbert transformation of the context. Signals of the aforementioned forms are called analytic signals [3].

The Hilbert transformation operator for a simply-connected region Ω is related to the Plemelj formula of the context [4]. Let f be a 'good' holomorphic function in Ω such that it has non-tangential boundary limits almost everywhere on the boundary $\partial\Omega$. By denoting the boundary limit function as $\tilde{f} = u + iv$, where u and v are real-valued, we call v the Hilbert transform of u . Note that both u and v are defined on $\partial\Omega$. It is a fundamental result that functions in the complex Hardy spaces have non-tangential boundary limits almost everywhere on the boundary. The Hilbert transforms of the square integrable functions on the unit disc are given by the following [5]:

$$Hu(t) = \frac{1}{2\pi} \lim_{\epsilon \rightarrow 0} \int_{|t-s|>\epsilon} \cot\left(\frac{t-s}{2}\right) u(e^{is}) ds$$

The Hilbert transformation has a Fourier multiplier representation:

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$$Hu(t) = \sum_{n=-\infty}^{\infty} (-i \operatorname{sgn}(n)) c_n e^{int}, \quad u(t) = \sum_{n=-\infty}^{\infty} c_n e^{int}, \quad \sum_{n=-\infty}^{\infty} |c_n|^2 < \infty,$$

where $\operatorname{sgn}(\xi)$ is the signum function, being of the value $+1$ or -1 , respectively, for $\xi > 0$ or $\xi < 0$; and $\operatorname{sgn}(0) = 0$.

From now on, we assume that functions to be studied in $L^2(\partial\mathbf{D})$ are real valued. Under such assumption, while both f and Hf are real valued. Denote $f^\pm = \frac{1}{2}(f \pm iHf) \pm c_0/2$. Because of the relation $c_{-n} = \overline{c_n}$, we have

$$f = f^+ + f^-, \quad f = 2\operatorname{Re}f^+ - c_0. \tag{1.1}$$

We note that for any $f \in L^2(\partial\mathbf{D})$, not necessarily real valued, the Plemelj formula inside the disc is

$$\lim_{r \rightarrow 1^-} \frac{1}{2\pi i} \int_{\partial\mathbf{D}} \frac{f(\zeta)}{\zeta - re^{it}} d\zeta = \frac{1}{2}(f(e^{it}) + iHf(e^{it})) + \frac{c_0}{2}, \quad \text{a.e.},$$

and, in the L^2 -convergence sense,

$$f^+(e^{it}) = \sum_{k=0}^{\infty} c_k e^{ikt}, \quad f^-(e^{it}) = \sum_{k=-\infty}^{-1} c_k e^{ikt}.$$

For a real-valued function f , the second relation in (1.1) shows that a series expansion of f^+ gives rise to a series expansion of f . AFD is an adaptive decomposition (expansion) for f^+ into a linear combination of parameterized Szegő and higher-order Szegő kernels of the context. On the disc, the L^2 -normalized Szegő kernels alone constitute a dictionary, called *Szegő Dictionary*,

$$\mathcal{D} = \{e_a\}_{a \in \mathbf{D}}, \quad e_a(z) = \frac{\sqrt{1 - |a|^2}}{1 - \bar{a}z}.$$

A Szegő kernel has the remarkable property that it is the reproducing kernel of the underlying Hardy space: Under the inner product

$$\langle f, g \rangle = \frac{1}{2\pi} \int_0^{2\pi} f(e^{it}) \bar{g}(e^{it}) dt,$$

there holds

$$\langle f, e_a \rangle = \sqrt{1 - |a|^2} f(a). \tag{1.2}$$

We note that AFD not only gives a series in Szegő and higher-order Szegő kernels that fast converges to the targeted function [2] but also gives rise to a positive frequency representation of the function with considerable stability [1, 6]. The recent studies of positive instantaneous frequency and related signal decomposition were motivated by related work in signal analysis area, including those of Picinbono [6], Cohen [7], and Huang *et al.* [8]. We note that in spite of the desires and efforts, EMD of Huang *et al.* [8] does not generate positive analytical instantaneous frequency, nor what they called HHT [9]. Studies show that theoretical development of this theme has to involve complex Hardy spaces, and, especially, the inner and outer functions theory of Nevanlinna in complex analysis.

In rational approximation of one complex variable, one cannot avoid the so-called rational orthogonal systems, or alternatively, Takenaka–Malmquist (TM) systems [10, 11]. The functions in a TM system are obtained, in fact, from the Gram–Schmidt (G-S) orthogonalization process applied to the *partial fractions* E_k , essentially the parameterized Szegő and higher-order Szegő kernels, defined as follows. Let $\{a_1, \dots, a_n\}$ be an n -tuple of complex numbers in \mathbf{D} . We say that an entry a_k of the n -tuple $\{a_1, \dots, a_n\}$ has the multiplicity m_k , if there exist exactly m_k entries $a_{n_1}, \dots, a_{n_{m_k}}$ with $1 \leq n_1 < \dots < n_{m_k} = k$ such that $a_{n_1} = \dots = a_{n_{m_k}} = a_k$. Given an n -tuple $\{a_1, \dots, a_n\}$, we define

$$E_k(z) = E_{\{a_1, \dots, a_k\}}(z) := \begin{cases} \frac{1}{(1 - \bar{a}_k z)^{m_k}} & \text{if } a_k \neq 0 \\ z^{m_k - 1} & \text{if } a_k = 0, \end{cases} \tag{1.3}$$

where m_k is the multiplicity of $a_k, k = 1, \dots, n$. We say that E_k is a higher-order Szegő kernel if $m_k > 1$; and otherwise, a *Szegő kernel*. The system $\{E_1, E_2, \dots, E_n\}$ is called the partial fraction system generated by $\{a_1, \dots, a_n\}$. It is usually not orthogonal. A TM system, as denoted by $\{B_k\}_{k=1}^n$ in the sequel, is the result of the G-S orthogonalization process applied to a partial fraction system $\{E_k\}_{k=1}^n$ [11, 12]. In the sequel, we will call the dictionary consisting of all the normalized partial fractions, viz., the normalized Szegő and higher-order Szegő kernels given in (1.3), the *Complete Szegő Dictionary*, denoted by $\tilde{\mathcal{D}}$ (Section 4).

In this article, we generalize the theory in the unit disc to poly-discs. The 2-disc theory, in particular, like multiple Fourier series, has direct applications to image analysis and image processing.

In the unit disc context, a TM system is an infinite sequence of parameterized rational functions

$$B_k(z) = \frac{\sqrt{1 - |a_k|^2}}{1 - \bar{a}_k z} \prod_{l=1}^{k-1} \frac{z - a_l}{1 - \bar{a}_l z}, \quad k = 1, 2, \dots,$$

where a_1, \dots, a_k, \dots are any complex numbers in the open unit disc. The multiple product part of each B_k is a Blaschke product with $k - 1$ zeros, being the product of the explicitly given $(k - 1)$ Möbius transforms, while the rest part is a normalized Szegő kernel, being an element of the dictionary \mathcal{D} , where we treat the complex number a as a parameter. Such systems have been well studied. In particular, when all the a_k 's are identical with zero, $\{B_k\}$ reduces to a half of the Fourier system, viz., $\{z^{k-1}\}_{k=1}^\infty$, a basis of the Hardy spaces. It is known that for general parameters a_k 's, a system $\{B_k\}$ is a basis of the Hardy space H^p on the disc, $1 \leq p \leq \infty$, if and only if the hyperbolic non-separability condition is satisfied, viz., [11]

$$\sum_{k=1}^\infty (1 - |a_k|) = \infty \tag{1.4}$$

For $p = 2$, the TM system is an orthonormal basis of $H^2(\mathbf{D})$ if and only if the condition (1.4) is met.

It is noted that writing in the form $B_k(e^{it}) = \rho_k(t)e^{i(\psi_k(t) + \phi_{k-1}(t))}$, where $e_{a_k}(e^{it}) = \rho_k(t)e^{i\psi_k(t)}$, $\rho_k(t) \geq 0$, $e^{i\phi_{k-1}(t)} = \prod_{l=1}^{k-1} \frac{e^{it} - a_l}{1 - \bar{a}_l e^{it}}$, we have $\phi'_{k-1}(t) \geq 0$ and $1 + \psi'_k(t) > 0$ for all $t \in [0, 2\pi]$, $k = 1, 2, \dots$, $\phi'_0 = 0$. In particular, if $a_1 = 0$, then $\psi'_k(t) + \phi'_{k-1}(t) \geq 0$ for all t and $k = 1, 2, \dots$ [1]. A representation into a linear combination of such B_k 's is a positive instantaneous frequency decomposition, or alternatively, a mono-component (Hardy space functions of positive analytic phase derivative almost everywhere) decomposition [1, 6, 7, 13–15]. In fact, it was the seeking for such decompositions that motivated 1-D AFD.

To make easy understanding to 2-D AFD delivered in Section 2 and also for the self-containing purpose, we now give an exposition for the existing 1-D AFD [1, 2]. Let f belong to the Hardy space $H^2(\mathbf{D})$. Set $f_1 = f$. For any $a_1 \in \mathbf{D}$, we have the identity

$$f(z) = \langle f_1, e_{a_1} \rangle e_{a_1}(z) + f_2(z) \frac{z - a_1}{1 - \bar{a}_1 z}, \tag{1.5}$$

with

$$f_2(z) = \frac{f_1(z) - \langle f_1, e_{a_1} \rangle e_{a_1}(z)}{\frac{z - a_1}{1 - \bar{a}_1 z}}.$$

Because of the reproducing kernel property of e_{a_1} in $H^2(\mathbf{D})$, we have

$$\langle f, e_{a_1} \rangle = \sqrt{1 - |a_1|^2} f(a_1), \quad \text{and hence,} \quad f_1(a_1) - \langle f_1, e_{a_1} \rangle e_{a_1}(a_1) = 0.$$

The last assertion implies that $f_2 \in H^2(\mathbf{D})$ that enables the recursive process in the sequel. We call the transformation from f_1 to f_2 the *generalized backward shift via a_1* ; and f_2 , the *reduced remainder*, being the *generalized backward shift transform* of f_1 via a_1 . Such terminology was motivated by the classical backward shift operator

$$S(f)(z) = \sum_{k=0}^\infty c_{k+1} z^k = \frac{f(z) - f(0)}{z},$$

where we assume $f(z) = \sum_{k=0}^\infty c_k z^k$. Noticing that $f(0) = \langle f, e_0 \rangle e_0(z)$, S is identical with the just defined generalized backward shift operator via 0.

Because of the orthogonality between the two terms on the right-hand side of (1.5) and the unimodular property of Möbius transforms on the boundary, we have

$$\|f\|^2 = \|\langle f_1, e_{a_1} \rangle e_{a_1}\|^2 + \|f_2 \frac{(\cdot) - a_1}{1 - \bar{a}_1(\cdot)}\|^2 = |\langle f_1, e_{a_1} \rangle|^2 + \|f_2\|^2.$$

We are to select $a_1 \in \mathbf{D}$ that gives the term $\langle f_1, e_{a_1} \rangle e_{a_1}(z)$ the maximal energy out of $\|f\|^2$. Because of the reproducing kernel property of e_{a_1} , we have

$$|\langle f_1, e_{a_1} \rangle|^2 = (1 - |a_1|^2) |f_1(a_1)|^2, \tag{1.6}$$

and, hence, we are reduced to find $a_1 \in \mathbf{D}$ such that

$$a_1 = \arg \max\{(1 - |a|^2) |f_1(a)|^2 : a \in \mathbf{D}\}.$$

The existence of such maximal selection is evident ([1], it can also be referred to the proofs of Theorems 2.3 and 3.1 in the succeeding text) and called *Maximal Selection Principle*. Having selected such a_1 , we repeat the same procedure to f_2 , and so on. After consecutive n steps, we obtain

$$f(z) = \sum_{k=1}^n \langle f_k, e_{a_k} \rangle B_k(z) + f_{n+1} \prod_{k=1}^n \frac{z - a_k}{1 - \bar{a}_k z},$$

where for $k = 1, \dots, n$,

$$a_k = \arg \max\{(1 - |a|^2)|f_k(a)|^2 : a \in \mathbf{D}\}, \tag{1.7}$$

and, for $k = 2, \dots, n + 1$,

$$f_k(z) = \frac{f_{k-1}(z) - \langle f_{k-1}, e_{a_{k-1}} \rangle e_{a_{k-1}}(z)}{\frac{z - a_{k-1}}{1 - \bar{a}_{k-1} z}}.$$

Because of the orthogonality, we have

$$\|f - \sum_{k=1}^n \langle f_k, e_{a_k} \rangle B_k(z)\|^2 = \|f\|^2 - \sum_{k=1}^n |\langle f_k, e_{a_k} \rangle|^2 = \|f_{k+1}\|^2.$$

It can be shown that

$$\lim_{n \rightarrow \infty} \|f_{k+1}\| = 0$$

[1], and thus

$$f(z) = \sum_{k=1}^{\infty} \langle f_k, e_{a_k} \rangle B_k(z). \tag{1.8}$$

The decomposition of f given by (1.8) is called adaptive Fourier decomposition (AFD) of f .

The following relations are noted:

$$\langle f_k, e_{a_k} \rangle = \langle g_k, B_k \rangle = \langle f, B_k \rangle, \tag{1.9}$$

where g_k is the orthogonal standard remainder defined through

$$f = \sum_{i=1}^{k-1} \langle f, B_i \rangle B_i(z) + g_k(z). \tag{1.10}$$

We also cite the useful relations

$$g_k(z) = f_k(z) \prod_{l=1}^{k-1} \frac{z - a_l}{1 - \bar{a}_l z}, \quad \text{where } f_k = S_{a_{k-1}} \cdots S_{a_1} f(z). \tag{1.11}$$

To deal with the convergence rate issue, we define a particular subclass of functions [2]:

$$H^2(\mathcal{D}, M) := \{f \in H^2(D) : f = \sum_{k=1}^{\infty} c_k e_k, e_k \in \mathcal{D}, \sum_{k=1}^{\infty} |c_k| \leq M\}, \quad 0 < M < \infty. \tag{1.12}$$

We have the following [2]:

Theorem 1.1

Let \mathcal{D} be the dictionary of the normalized Szegő kernels of $H^2(D)$. Then for each $f \in H^2(\mathcal{D}, M)$, decomposed by AFD, we have

$$\|g_k\| \leq \frac{M}{\sqrt{k}}.$$

We note that functions in the class $H^2(\mathcal{D}, M)$ may not be smooth on the unit circle. The aforementioned estimation in the energy sense reflects the tolerance of AFD with non-smoothness.

Remark 1

There are variations of 1-D AFD (also called Core AFD in later references as it is the construction block of the other AFDs based on maximal selections) of which we mention unwinding AFD [16], cyclic AFD [17], and higher-order-Szegő-kernel AFD [18]. Each of the mentioned AFD variations has its own merits. In particular, unwinding and higher-order-Szegő-kernel AFDs are designed for decompose signals of high frequencies. Cyclic AFD offers a conditional solution for the open problem of finding a rational Hardy space function, whose degree does not exceed a pre-described integer n that best approximates a given Hardy space function [17].

Remark 2

One-dimensional adaptive Fourier decomposition and its variations have found significant applications to system identification and signal analysis [19–22].

Remark 3

Any complete TM system with $a_1 = 0$ gives rise to signal decompositions of positive frequencies. To sufficiently characterize a signal, it is desirable to find the most suitable TM systems for the given signal. The suitability may be measured by the corresponding convergence speed. It was the effort of gaining fast convergence that made AFD to share the same idea as greedy algorithm.

Remark 4

One-dimensional adaptive Fourier decomposition, as a matter of fact, is not the same as any existing greedy algorithm. In the last section of this article, we will introduce a new greedy algorithm called *Pre-orthogonal Greedy Algorithm (P-OGA)* and will show that P-OGA is identical with AFD in the unit disc context. Among the existing greedy algorithms, including the weak type ones, the one that is most close to P-OGA is orthogonal greedy algorithm (OGA). In AFD, at the step n , a parameter value a_n can be repeatedly selected with respect to the reduced remainder f_n in order to have the maximal energy gain. On the other hand, OGA does not allow repeated selections of a parameter with respect to the orthogonal standard remainder g_n . In the unit disc context, OGA generates orthogonal projections of the orthogonal standard remainder g_n into linear span of

$$1, \frac{1}{1 - \bar{a}_1 z}, \dots, \frac{1}{1 - \bar{a}_n z}, \quad n = 1, 2, \dots,$$

where all the a_k 's are distinct. In contrast, 1-D AFD, in accordance with (1.3), gives rise to orthogonal projections into linear spans of the partial fraction systems

$$1, \dots, z^{m_0-1}, \frac{1}{1 - \bar{a}_1 z}, \dots, \frac{1}{(1 - \bar{a}_1 z)^{m_1}}, \dots, \frac{1}{1 - \bar{a}_n z}, \dots, \frac{1}{(1 - \bar{a}_n z)^{m_n}}, \quad n = 1, 2, \dots, \quad (1.13)$$

where all the a_n are distinct and m_n are the respective multiples. The latter is with the full strength of the related partial fractions, and thus, the decomposition converges faster (also see Sections 2 and 3). Not only having a fast converging positive frequency representation, AFD through its backward shift process automatically generates an orthogonal expansion without involving the G-S orthogonalization process.

Remark 5

The Maximal Selection Principle may produce a sequence a_1, \dots, a_n, \dots that does not satisfies (1.4). Such case corresponds to a remarkable decomposition of the Hardy space. It is noted that the case is exactly when a Blaschke product $\phi(z)$ is definable with a_1, \dots, a_k, \dots , being all its zeros including the multiples [5]. In such case, we have the space decomposition

$$H^2 = \overline{\text{span}\{B_k\}} \oplus \phi H^2, \quad (1.14)$$

where the closed set $\overline{\text{span}\{B_k\}}$ is a *backward shift invariant subspace* and ϕH^2 a *shift invariant subspace* of the H^2 space. In such case, f belongs to the backward shift invariant space. Backward shift invariant subspaces have significant applications to phase and amplitude retrieval problems and solutions of the Bedrosian equations, as well as to system identification [21]. We note that for the index range $1 < p < \infty$, no matter whether (1.4) is met or not, the generalized system $\{B_k\}$ is a Schauder basis of the $L^p(\partial\mathbf{D})$ -topological closure of the $\text{span}\{B_k\}$ [22].

Now, we discuss whether the idea of AFD can be generalized to multiple dimensions. AFD is based on complex analysis of one complex variable. For a Euclidean space \mathbf{R}^n , there exist essentially two formulations to bring in a complex structure, or a Cauchy theory. One is the several complex variables formulation with the imbedding $\mathbf{R}^n \subset \mathbf{C}^n$. It changes a function of several real variables, $f(x_1, \dots, x_n)$, to the corresponding one in several complex variables, $f(z_1, \dots, z_n)$. This makes sense at least when f is a polynomial. In such formulation, f is said to be holomorphic if and only if f is holomorphic in each component variable $z_k, k = 1, 2, \dots, n$. The other is the imbedding into a Clifford algebra, with the quaternionic space as a particular case. The formulation extends the domain of a function $f(x_1, \dots, x_n)$ to a set of one more dimension, $f(x_0, x_1, \dots, x_n)$. With each of those formulations, there exists a Hardy space theory. In the several complex variables case, there exist Hardy spaces on tubes [23, 24]; while, for the Clifford algebra formulation, there exists a conjugate harmonic system theory [23, 24], being alternative to the notion of Clifford Hardy space theory [25, 26]. The Clifford-quaternionic formulation is more close to one complex variable: 1-D AFD has been extended or partially extended to the quaternionic and the Clifford algebra contexts. The first paper along this line is [27] generalizing AFD to quaternions. The second paper is [28] dealing with general Clifford algebras. Because of the non-commutativity obstacle, what one can do in \mathbf{R}^n is a greedy-like algorithm. The AFD generalizations to those contexts are not in full because of the non-commutative obstacle. The third paper is [29] in which a scalar-valued phase and its derivative are introduced and used to analyze signals of several real variables. The phase derivative concept has a close connection with signal decomposition. The success of the generalizations to the quaternionic-Clifford algebra formulation lies on the fact that one can perform algebraic computations to higher-dimensional vectors just like what one does to complex numbers. The inconvenience of such formulation is that, except the two cases, viz., the whole hyper-planes and the real spheres in \mathbf{R}^n , there exist very few cases in which we could possibly use the quaternionic and Clifford algebra theory. For images defined in bounded regions, including rectangular regions for instance, one runs into difficulty.

For the several complex variables formulation, there is no direct and parallel method like what we use in the 1-D case to produce an AFD theory. In particular, there is no backward shift mechanism, nor outer functions theory, nor Blaschke products either. The present study offers two approaches for the several complex variables formulation of which one is phrased as ‘Product-TM Systems’; and the other ‘Product-Szegő Dictionary’, as provided, respectively, in Sections 2 and 3. With the Product-TM System approach, like in the 1-D theory, we prove a Maximal Selection Principle and then prove the corresponding convergence. With the Product-Szegő Dictionary approach, we first show that OGA is applicable, that is, the maximal energy may be gained at each step. We next propose a new type greedy algorithm in the abstract complex Hilbert space setting, called Pre-orthogonal Greedy Algorithm, abbreviated as P-OGA. Our proofs of the corresponding convergence and convergence rate estimation are made to be more general by allowing the weak type version. To be consistent with the literature, by ‘weak’, we mean to allow a tolerance constant $\rho < 1$ in the Maximal Selection Principle (3.24). The new convergence rate estimation (Theorem 3.3) evidences that P-OGA is stronger than OGA). In Section 4, we further study P-OGA in depth and raise a new concept *Induced Complete Dictionary*, or Complete Dictionary. We show that the concept is naturally associated with P-OGA. We then prove the availability of P-OGA in the 2-torus context under the Complete Dictionary Induced by the Product-Szegő Dictionary. Finally, we prove that in the classical 1-D unit disc context, under the Complete Dictionary Induced from the Szegő Dictionary, P-OGA is identical with AFD.

2. 2-D AFD of the Product-TM System type

We will be working with two complex variables. For more several complex variables, there is a parallel theory.

Let \mathbf{a} denote a finite or infinite sequence $\{a_n\}$ of complex numbers a_1, a_2, \dots in the unit disc \mathbf{D} , and $\mathcal{B}^{\mathbf{a}}$ the finite or infinite TM system defined through \mathbf{a} , that is,

$$\mathcal{B}^{\mathbf{a}} = \{B_{\{a_1, \dots, a_n\}}\} = \{B_n^{\mathbf{a}}\},$$

where

$$B_n^{\mathbf{a}}(z) = \frac{\sqrt{1 - |a_n|^2}}{1 - \bar{a}_n z} \prod_{l=1}^{n-1} \frac{z - a_l}{1 - \bar{a}_l z}, \quad n = 1, 2, \dots$$

When \mathbf{a} is a finite sequence, $\mathbf{a} = \{a_1, \dots, a_N\}$, we sometimes denote $\mathcal{B}^{\mathbf{a}}$ by $\mathcal{B}_N^{\mathbf{a}}$.

Let \mathbf{T} denote the boundary of the unit disc $\partial\mathbf{D}$, and $L^2(\mathbf{T}^2)$ the space of complex-valued functions on the 2-torus with finite energy, where the energy is defined via the inner product

$$\langle f, g \rangle = \frac{1}{4\pi^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} f(e^{it}, e^{is}) \bar{g}(e^{it}, e^{is}) dt ds.$$

From the multiple trigonometric series theory, $f \in L^2(\mathbf{T}^2)$ if and only if

$$f(e^{it}, e^{is}) = \sum_{-\infty < k, l < \infty} c_{kl} e^{i(kt+ls)} \quad \text{in the } L^2 \text{ - sense,}$$

where

$$\sum_{-\infty < k, l < \infty} |c_{kl}|^2 < \infty, \quad c_{kl} = \langle f, e_{kl} \rangle, \quad e_{kl}(t, s) = e^{ikt} e^{ils}.$$

Denote

$$H^2(\mathbf{T}^2) = \{f \in L^2(\mathbf{T}^2) : f(e^{it}, e^{is}) = \sum_{k, l \geq 0} c_{kl} e^{i(kt+ls)}\}.$$

In the sequel, if there is no confusion arising, we will denote $L^2(\mathbf{T}^2)$ and $H^2(\mathbf{T}^2)$, briefly and respectively, by H^2 and L^2 . It can be easily shown that H^2 is a closed subspace of L^2 . Denote by $H^2(\mathbf{D}^2)$, the class of complex holomorphic functions in the poly-disc $\mathbf{D} \times \mathbf{D}$ satisfying

$$\sup_{0 < r, s < 1} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} |f(re^{it}, se^{iu})|^2 dt du < \infty.$$

It may be shown that for any function $f \in H^2(\mathbf{D}^2)$, there holds

$$\lim_{z \rightarrow e^{it}; w \rightarrow e^{is}} f(z, w) \quad \text{exist for almost all } (e^{it}, e^{is}) \in \mathbf{T}^2,$$

where both the limits $z \rightarrow e^{it}$ and $w \rightarrow e^{is}$ are in the non-tangential manner in their respective unit disc, and the limit function on \mathbf{T}^2 belongs to $H^2(\mathbf{T}^2)$. The mapping that maps a function in $f \in H^2(\mathbf{D}^2)$ to its boundary limit function in $H^2(\mathbf{T}^2)$ is one to one and onto, and, as a matter of fact, an isometric isomorphism. For this reason, we sometimes use H^2 for both $H^2(\mathbf{D}^2)$ and $H^2(\mathbf{T}^2)$. We note that \mathbf{T}^2 is not the topological boundary, but *characteristic boundary* of \mathbf{D}^2 , which is part of the topological boundary. Data on the characteristic boundary, however, determine a holomorphic function inside \mathbf{D}^2 through the Cauchy integral with the tensor type Cauchy kernel of two complex variables.

From now on, we work with a real-valued function $f \in L^2$. Define

$$\begin{aligned} f^{+,+}(e^{it}, e^{is}) &= \sum_{k,l \geq 0} c_{lk} e^{i(kt+ls)}, \\ f^{+,-}(e^{it}, e^{is}) &= \sum_{k,-l \geq 0} c_{lk} e^{i(kt+ls)}, \\ f^{-,+}(e^{it}, e^{is}) &= \sum_{-k,l \geq 0} c_{lk} e^{i(kt+ls)}, \\ f^{-,-}(e^{it}, e^{is}) &= \sum_{-k,-l \geq 0} c_{lk} e^{i(kt+ls)}. \end{aligned}$$

Analogous with (1.1), we have

Theorem 2.1

Let $f \in L^2$ be real valued. Then

$$f(e^{it}, e^{is}) = 2\text{Re} \{f^{+,+}\}(e^{it}, e^{is}) + 2\text{Re} \left[f(e^{i(\cdot)}, e^{-i(\cdot)}) \right]^{+,+}(e^{it}, e^{-is}) - 2\text{Re} \{F^+\}(e^{it}) - 2\text{Re} \{G^+\}(e^{is}) + c_{00}.$$

Proof

We have the relation

$$f(e^{it}, e^{is}) + F(e^{it}) + G(e^{is}) + c_{00} = f^{+,+}(e^{it}, e^{is}) + f^{+,-}(e^{it}, e^{is}) + f^{-,+}(e^{it}, e^{is}) + f^{-,-}(e^{it}, e^{is}),$$

where

$$F(e^{it}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(e^{it}, e^{is}) ds, \quad G(e^{is}) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(e^{it}, e^{is}) dt.$$

Therefore,

$$f(e^{it}, e^{is}) = f^{+,+}(e^{it}, e^{is}) + f^{+,-}(e^{it}, e^{is}) + f^{-,+}(e^{it}, e^{is}) + f^{-,-}(e^{it}, e^{is}) - F(e^{it}) - G(e^{is}) - c_{00}.$$

We note that

$$\left[f(e^{i(\pm\cdot)}, e^{i(\pm\cdot)}) \right]^{+,+}(e^{i(\pm t)}, e^{i(\pm s)}) = f^{\pm,\pm}(e^{it}, e^{is}), \quad \left[f(e^{i(\pm\cdot)}, e^{i(\mp\cdot)}) \right]^{+,+}(e^{i(\pm t)}, e^{i(\mp s)}) = f^{\pm,\mp}(e^{it}, e^{is}).$$

Because f is real valued, $f^{+,+}$ and $f^{-,-}$ are a conjugate pair, and $f^{+,-}$ and $f^{-,+}$ are another conjugate pair. We have

$$f^{+,+} + f^{-,-} = 2\text{Re} \{f^{+,+}\}$$

and

$$f^{+,-} + f^{-,+} = 2\text{Re} \{f^{+,-}\}.$$

Thus,

$$\begin{aligned} f(e^{it}, e^{is}) &= 2\text{Re} \{f^{+,+}\}(e^{it}, e^{is}) + 2\text{Re} \{f^{+,-}\}(e^{it}, e^{is}) - F(e^{it}) - G(e^{is}) - c_{00} \\ &= 2\text{Re} \{f^{+,+}\}(e^{it}, e^{is}) + 2\text{Re} \left[f(e^{i(\cdot)}, e^{-i(\cdot)}) \right]^{+,+}(e^{it}, e^{-is}) - F(e^{it}) - G(e^{is}) - c_{00} \\ &= 2\text{Re} \{f^{+,+}\}(e^{it}, e^{is}) + 2\text{Re} \left[f(e^{i(\cdot)}, e^{-i(\cdot)}) \right]^{+,+}(e^{it}, e^{-is}) - 2\text{Re} \{F^+\}(e^{it}) - 2\text{Re} \{G^+\}(e^{is}) + c_{00}. \end{aligned}$$

The proof is complete. □

We note that $f^{+,+}(e^{it}, e^{is}), f^{+,-}(e^{it}, e^{-is}), f^{-,+}(e^{-it}, e^{is}), f^{-,-}(e^{-it}, e^{-is})$ are functions in H^2 . The aforementioned result shows that decomposition of a real-valued function $f \in L^2$ may be reduced to decomposition of a number of related functions in the Hardy space.

It may be easily shown that the Product-TM System is complete in the product space, if the two factor 1-D TM systems both are complete in their respective spaces.

Theorem 2.2

If \mathcal{B}_N^a and \mathcal{B}_M^b are two finite TM systems, then $\mathcal{B}_N^a \otimes \mathcal{B}_M^b$ is an orthonormal system in $L^2(\mathbf{T}^2)$. When \mathcal{B}^a and \mathcal{B}^b are two bases of $H^2(\mathbf{T})$, then $\mathcal{B}^a \otimes \mathcal{B}^b$ is a basis of $H^2(\mathbf{T}^2)$.

Proof

The first assertion is obvious. To show the second, we note that holomorphic functions in two complex variables of the type $\sum_{k=1}^K f_k(z)g_k(w)$ are dense in $H^2(\mathbf{T}^2)$. In fact, finite sums of multiple trigonometric series are dense in $H^2(\mathbf{T}^2)$. If \mathcal{B}^a and \mathcal{B}^b are two bases of $H^2(\mathbf{T})$, then finite linear combinations of functions in $\mathcal{B}^a \otimes \mathcal{B}^b$ are dense in the function class consisting of functions of the type $\sum_{k=1}^K f_k(z)g_k(w)$ and therefore also dense in $H^2(\mathbf{T}^2)$. The proof is complete.

Denote, for $f \in H^2(\mathbb{T}^2)$,

$$S_n(f) = \sum_{1 \leq k, l \leq n} \langle f, B_k^a \otimes B_l^b \rangle B_k^a \otimes B_l^b = \sum_{k=1}^n D_n(f), \quad D_n(f) = S_n(f) - S_{n-1}(f), \quad S_0(f) = 0, \quad (2.15)$$

$$n = 1, 2, \dots$$

□

Note that $D_n(f)$ is called the n -partial sum difference having $2n - 1$ entries.

Theorem 2.3 (Maximal selection principle for Product-TM System)

For any $f \in H^2$ and previously fixed a_1, \dots, a_{n-1} and b_1, \dots, b_{n-1} in \mathbf{D} , there exist a_n, b_n in \mathbf{D} such that the associated

$$\|D_n(f)\|^2 = \sum_{\max\{k,l\}=n} |\langle f, B_k^a \otimes B_l^b \rangle|^2 \quad (2.16)$$

attains its maximal value among all possible selections of a_n, b_n inside the unit disc.

Proof

Let $f \in H^2$ be given and fixed. We separate the proof into two steps: (i) when $|a_n| \rightarrow 1$ and $|b_n| \rightarrow 1$, with a_1, \dots, a_{n-1} and b_1, \dots, b_{n-1} being previously fixed, one has, uniformly in a_1, \dots, a_{n-1} and b_1, \dots, b_{n-1} ,

$$\lim_{|a_n| \rightarrow 1, |b_n| \rightarrow 1} \|D_n(f)\|^2 = 0;$$

and (ii) if one of $|a_n|$ and $|b_n|$ tends to 1, then (2.16) does not give rise to a maximal value either. We note that the first assertion deals with the case where (a_n, b_n) tends to the characteristic boundary; while the second assertion deals with the boundary. □

Now we show (i). Applying the Cauchy–Schwarz inequality to each of the $2n - 1$ terms of the partial sum difference D_n , we conclude that, for any $\epsilon > 0$, we can find a polynomial P such that

$$\|D_n(f - P)\|^2 \leq \epsilon$$

uniformly in a_1, \dots, a_{n-1}, a_n and b_1, \dots, b_{n-1}, b_n . It is therefore reduced to showing that for any polynomial P ,

$$\lim_{|a_n| \rightarrow 1, |b_n| \rightarrow 1} \|D_n(P)\|^2 = 0.$$

Now, because of the expansion of D_n in (2.15), it suffices to show, under the limit procedure $|a_n| \rightarrow 1$ and $|b_n| \rightarrow 1$,

$$|\langle P, B_n^a \otimes B_l^b \rangle|^2 \rightarrow 0, \quad 1 \leq l \leq n \quad (2.17)$$

and

$$|\langle P, B_k^a \otimes B_n^b \rangle|^2 \rightarrow 0, \quad 1 \leq k < n. \quad (2.18)$$

Denote by $S_a^{(1)}$ the generalized partial backward shift operator via a for the variable z , and similarly $S_b^{(2)}$ for the second variable w . Because of (1.11), as well as the reproducing property of the product Szegő kernel $e_{a_n} \otimes e_{b_n}$, we have

$$\begin{aligned} \langle P, B_n^a \otimes B_l^b \rangle &= \left\langle \prod_{k=1}^{n-1} S_{a_k}^{(1)} \prod_{k=1}^{l-1} S_{b_k}^{(2)}(P), e_{a_n} \otimes e_{b_l} \right\rangle \\ &= \sqrt{1 - |a_n|^2} \sqrt{1 - |b_l|^2} \prod_{k=1}^{n-1} S_{a_k}^{(1)} \prod_{k=1}^{l-1} S_{b_k}^{(2)}(P)(a_n, b_l) \\ &\rightarrow 0, \quad \text{as } |a_n| \rightarrow 1, \end{aligned} \quad (2.19)$$

where we use the fact that generalized backwards shifts of polynomials are still polynomials and thus are bounded in a neighborhood of the closed unit disc. Similarly, we can show (2.18). We thus have

$$\lim_{|a_n| \rightarrow 1, |b_n| \rightarrow 1} \|D_n(P)\|^2 = 0.$$

Now, we show (ii). Let $|a_n| \rightarrow 1$. Because of (2.19), all terms in (2.17) are vanishing. The orthogonality between the $2n - 1$ terms of $D_n(f)$ implies that for $|a_n| \rightarrow 0$, only the terms corresponding to (2.18) can contribute to the energy gain, and thus do not give rise to the maximal energy, unless for all a_n , the terms in (4.36) are zero. In the latter case, the remainder after the former $n - 1$ steps depends only on the variable w , reducing to one complex variable case. In any case, the maximal energy is attained only at an interior point. The proof is complete.

Thanks to orthogonality between distinct $B_k^a \otimes B_l^b$'s, there follows

$$0 \leq \|f - \sum_{k=1}^n D_k(f)\|^2 = \|f\|^2 - \sum_{k=1}^n \|D_k(f)\|^2$$

that implies the Bessel inequality

$$\sum_{k=1}^n \|D_k(f)\|^2 \leq \|f\|^2.$$

As a consequence, we have

$$\lim_{n \rightarrow \infty} \sum_{k=n+1}^{\infty} \|D_k(f)\|^2 = 0.$$

This, in particular, is valid with maximal selections of (a_n, b_n) in accordance with Theorem 2.3. Moreover, under such selections, we have

Theorem 2.4

Let $f \in H^2(\mathbb{T}^2)$. For any k_0 and previously fixed $a_1, b_1, \dots, a_{k_0-1}, b_{k_0-1}$, by selecting parameter pairs $(a_{k_0}, b_{k_0}), (a_{k_0+1}, b_{k_0+1}), \dots$, according to the Maximal Selection Principle, we have

$$\lim_{n \rightarrow \infty} \|f - S_n(f)\|^2 = 0.$$

In other words, in the L^2 -convergence sense,

$$f = \lim_{n \rightarrow \infty} S_n(f).$$

Proof

We prove this by contradiction. Assume that this is not true. Then

$$f = \sum_{k=1}^{\infty} D_k(f) + h, \quad h \neq 0,$$

where h is in H^2 and orthogonal with each $D_k(f)$. Hence,

$$\|h\|^2 = \|f\|^2 - \sum_{k=1}^{\infty} \|D_k(f)\|^2 > 0.$$

By using the tensor type Cauchy formula for two complex variables, we have for any \tilde{a}, \tilde{b} in \mathbf{D} ,

$$\langle h, e_{\{\tilde{a}\}} \otimes e_{\{\tilde{b}\}} \rangle = \sqrt{1 - |\tilde{a}|^2} \sqrt{1 - |\tilde{b}|^2} h(\tilde{a}, \tilde{b})$$

Therefore, there exist \tilde{a}, \tilde{b} in the unit disc such that $\langle h, e_{\{\tilde{a}\}} \otimes e_{\{\tilde{b}\}} \rangle \neq 0$. Denote by

$$\tilde{X} = \overline{\text{span}}\{\tilde{B}^{\tilde{a}} \otimes \tilde{B}^{\tilde{b}}\},$$

where $\tilde{B}^{\tilde{a}}$ is the TM system generalized by $\{\tilde{a}, a_1, \dots, a_n, \dots\}$ under the given order; and likewise, for the notation $\tilde{B}^{\tilde{b}}$. The corresponding n -partial sum difference is denoted \tilde{D}_n , involving $\tilde{a}, \tilde{b}, a_1, b_1, \dots, a_{n-1}, b_{n-1}$. □

Denote by h/\tilde{X} the orthogonal projection of h into the subspace \tilde{X} . In the sequel, we will continue to adopt this notation for orthogonal projections. It is easy to show that

$$\|h/\tilde{X}\|_2 = \delta > 0.$$

In fact,

$$\|h/\tilde{X}\|_2^2 \geq \sum_{k=1}^{\infty} \|\tilde{D}_k\|_2^2 \geq \|\tilde{D}_1\|_2^2 = |\langle h, e_{\tilde{a}} \otimes e_{\tilde{b}} \rangle|^2 > 0.$$

Set, for any integer M ,

$$\tilde{X}_M = \text{span}\{\tilde{B}_M^{\tilde{a}} \otimes \tilde{B}_M^{\tilde{b}}\} \quad \text{and} \quad X_M = \text{span}\{B_M^{\tilde{a}} \otimes B_M^{\tilde{b}}\},$$

where $\tilde{B}_M^{\tilde{a}}$ and $\tilde{B}_M^{\tilde{b}}$ are, respectively, the TM systems generalized by $\{\tilde{a}, a_1, \dots, a_{M-1}\}$ and $\{\tilde{b}, b_1, \dots, b_{M-1}\}$.

Because

$$\|h/\tilde{X} - h/\tilde{X}_M\|^2 = \sum_{k=M+2}^{\infty} \|\tilde{D}_k\|^2 \rightarrow 0,$$

we have

$$\lim_{M \rightarrow \infty} h/\tilde{X}_M = h/\tilde{X}.$$

Now, find M so large that

$$\|h/\tilde{X}_M\|^2 > \delta/2 \quad \text{and} \quad \left\| \sum_{k=M}^{\infty} D_k(f) \right\|^2 < \delta/8.$$

For such M , on one hand,

$$\|f/X_M\|^2 = \left\| \sum_{k=1}^{M-1} D_k(f) \right\|^2 + \|D_M(f)\|^2 < \left\| \sum_{k=1}^{M-1} D_k(f) \right\|^2 + \delta/8,$$

that is for a maximal selection of (a_M, b_M) . On the other hand,

$$\|f/\tilde{X}_M\|^2 = \left\| \sum_{k=1}^{M-1} D_k(f) \right\|^2 + \left\| \left(\sum_{k=M}^{\infty} D_k(f) \right) / \tilde{X}_M + h/\tilde{X}_M \right\|^2 > \left\| \sum_{k=1}^{M-1} D_k(f) \right\|^2 + \delta/2 - \delta/8.$$

This shows that the selection (\tilde{a}, \tilde{b}) is better than the selection (a_M, b_M) , being contradictory to the maximality of the pair (a_M, b_M) . The proof of Theorem 2.4 is, therefore, complete.

The approximation algorithm in Theorem 2.4 is called *two-dimensional AFD (2-D AFD) of the Product-TM System type*.

3. 2-D AFDs of the Product-Szegő Dictionary type

We, in general, call all types of adaptive approximation by linear combinations of parameterized Szegő and higher-order Szegő kernels AFDs. We denote by

$$\mathcal{D}^2 = \{e_a \otimes e_b : a, b \in \mathbf{D}\}$$

the set of functions consisting of tensor products of two 1-D parameterized and normalized Szegő kernels. It is easy to show that \mathcal{D}^2 is a dictionary of the H^2 space of the poly-disc. We call it *Product-Szegő Dictionary*. We first verify that with the dictionary \mathcal{D}^2 the pure greedy algorithm (PGA) [30] is applicable to H^2 . Write

$$f(z, w) = \sum_{k=1}^{n-1} (\tilde{g}_k, e_{a_k} \otimes e_{b_k}) e_{a_k}(z) e_{b_k}(w) + \tilde{g}_n(z, w), \quad \tilde{g}_1 = f.$$

We note that the *standard remainders* \tilde{g}_n defined previously is different from what is defined in (1.10), the latter, being phrased as *orthogonal standard remainders*, related to the orthogonal projection of the given function to the linear space generated by the selected dictionary elements.

Because \tilde{g}_{k+1} is orthogonal with $e_{a_k} \otimes e_{b_k}$, we have the relation

$$\|\tilde{g}_{k+1}\|^2 = \|\tilde{g}_k - (\tilde{g}_k, e_{a_k} \otimes e_{b_k}) e_{a_k} \otimes e_{b_k}\|^2 = \|\tilde{g}_k\|^2 - |(\tilde{g}_k, e_{a_k} \otimes e_{b_k})|^2. \tag{3.20}$$

The associated energy rule is

$$\left\| f - \sum_{k=1}^n (\tilde{g}_k, e_{a_k} \otimes e_{b_k}) (e_{a_k} \otimes e_{b_k}) \right\|^2 = \|f\|^2 - \sum_{k=1}^n |(\tilde{g}_k, e_{a_k} \otimes e_{b_k})|^2,$$

which is obtained through recursive application of (3.20).

We show that for each k , the pair (a_k, b_k) can be selected such that

$$(a_k, b_k) = \arg \max\{|(\tilde{g}_k, e_a \otimes e_b)| : a, b \in \mathbf{D}\}.$$

Theorem 3.1 (Maximal Selection Principle for Product-Szegő Dictionary)

For any $\tilde{g} \in H^2(\mathbf{D}^2)$, one can find

$$(\tilde{a}, \tilde{b}) = \arg \max\{|(\tilde{g}, e_a \otimes e_b)| : a, b \in \mathbf{D}\}.$$

The proof of Theorem 2.3 by using polynomial approximation can be easily adapted to give a proof of Theorem 3.1. We, however, give an alternative proof that, by the author's opinion, has advantages in proving existence of the global maximum under simultaneous selections of several parameters [20]. The idea of the following proof was originated by Temlyakov [1, 31].

Proof

It suffices to show for any function \tilde{g} in the Hardy space there holds

$$\lim_{|a| \rightarrow 1^- \text{ or } |b| \rightarrow 1^-} |(\tilde{g}, e_a \otimes e_b)|^2 = 0.$$

□

Because of the orthogonality, it suffices to show

$$\lim_{|a| \rightarrow 1^- \text{ or } |b| \rightarrow 1^-} \|\tilde{g} - (\tilde{g}, e_a \otimes e_b)e_a \otimes e_b\| = \|\tilde{g}\|. \tag{3.21}$$

Let $P_r \otimes P_s$ be the tensor type Poisson kernel on the poly-disc [24], $r, s \in [0, 1)$. For $\epsilon > 0$, we can choose r and s sufficiently close to 1 such that, owing to the L^2 -approximation property of the Poisson integral, we have

$$\begin{aligned} \|\tilde{g}\| &\geq \|\tilde{g} - (\tilde{g}, e_a \otimes e_b)e_a \otimes e_b\| \\ &\geq \|(P_r \otimes P_s) * [\tilde{g} - (\tilde{g}, e_a \otimes e_b)e_a \otimes e_b]\| \\ &\geq \|(P_r \otimes P_s) * \tilde{g}\| - |(\tilde{g}, e_a \otimes e_b)| \|(P_r \otimes P_s) * (e_a \otimes e_b)\| \\ &\geq (1 - \epsilon)\|\tilde{g}\| - \|\tilde{g}\| \|(P_r \otimes P_s) * (e_a \otimes e_b)\|. \end{aligned} \tag{3.22}$$

Now, with the fixed r and s , because $e_a \otimes e_b \in H^2$, there follows, for $z = re^{it}, w = se^{iu}$,

$$(P_r \otimes P_s) * (e_a \otimes e_b)(e^{it}, e^{iu}) = e_a(z)e_b(w).$$

Then we have explicit computation

$$\begin{aligned} \|(P_r \otimes P_s) * (e_a \otimes e_b)\|^2 &= \frac{1}{(2\pi)^2} \int_0^{2\pi} \frac{1 - |a|^2}{|1 - \bar{a}re^{it}|^2} dt \int_0^{2\pi} \frac{1 - |b|^2}{|1 - \bar{b}se^{iu}|^2} du \\ &= \frac{1 - |a|^2}{1 - r^2|a|^2} \frac{1 - |b|^2}{1 - s^2|b|^2}. \end{aligned}$$

When $|a| \rightarrow 1$ or $|b| \rightarrow 1$, the inequality (3.22) gives

$$\|\tilde{g}\| \geq \|\tilde{g} - (\tilde{g}, e_a \otimes e_b)e_a \otimes e_b\| \geq (1 - 2\epsilon)\|\tilde{g}\|.$$

This shows that the limit (3.21) holds. The proof is complete.

By implementing the aforementioned Maximal Selection Principle with the Product-Szegő Dictionary, under the general theory of PGA [30, 32–34], one has, in the energy sense,

$$f = \sum_{k=1}^{\infty} \langle g_k, e_{a_k} \otimes e_{b_k} \rangle e_{a_k} \otimes e_{b_k}.$$

It was shown that OGA is more optimal than PGA [30, 33, 34]. In the succeeding text, we propose a new variation of greedy algorithm called P-OGA, which is truly stronger than OGA. Our formulation is in the general complex Hilbert space, allowing a weak type version of P-OGA, called WP-OGA.

Let \mathcal{H} be a complex Hilbert space and \mathcal{A} a dictionary consisting of elements $a \in \mathcal{A}$ satisfying $\|e_a\| = 1, \overline{\text{span}\mathcal{A}} = \mathcal{H}$. Let

$$f = \sum_{k=1}^{n-1} \langle f, B_k \rangle B_k + g_n, \tag{3.23}$$

where $\{B_1, \dots, B_k\}$ is the result of the G-S orthogonalization process applied to the finite system $\{a_1, \dots, a_k\}$, where for each k, a_k is selected to be one satisfying the *pre-orthogonal ρ -Maximal Selection Principle*

$$|\langle g_k, B_k \rangle| \geq \rho \sup\{|\langle g_k, B_k^a \rangle| : a \in \mathcal{A}\}, \quad \rho \in (0, 1], \tag{3.24}$$

where $\{B_1, \dots, B_{k-1}, B_k^a\}$ is the orthogonalization of $\{a_1, \dots, a_{k-1}, a\}$. Such defined decomposition is called *Weak Pre-orthogonal Greedy Algorithm*, abbreviated as WP-OGA. When $\rho = 1$, it is called *Pre-orthogonal Greedy Algorithm*, abbreviated as P-OGA. To see the difference between the just introduced with *Weak Orthogonal Greedy Algorithm* (WOGA, [30]), we recall that in the latter, the selected a_k satisfies

$$|\langle g_k, a_k \rangle| \geq \rho \sup\{|\langle g_k, a \rangle| : a \in \mathcal{A}\}, \quad \rho \in (0, 1]. \tag{3.25}$$

To summarize, both WP-OGA (P-OGA) and WOGA (OGA) use the orthogonal standard remainder, but WP-OGA first performs orthogonalization and then selects a dictionary element, while WOGA first selects a dictionary element and then performs orthogonalization. To show that WP-OGA offers a better approximation than OGA at each step, we note that, with a selected $a_k \in \mathcal{A}$, no matter how $|\langle g_k, a_k \rangle|$ is close to $\sup\{|\langle g_k, a \rangle| : a \in \mathcal{A}\}$, we always have

$$\sup\{|\langle g_k, B_k^a \rangle| : a \in \mathcal{A}\} \geq |\langle g_k, B_k^{a_k} \rangle|.$$

The optimality of WP-OGA is also seen from the convergence rate estimation proved in Theorem 3.3.

As in OGA, we have, owing to the orthogonality,

$$\langle f, B_k \rangle = \langle g_k, B_k \rangle.$$

The corresponding energy rule is again

$$\left\| f - \sum_{k=1}^n \langle f, B_k \rangle B_k \right\|^2 = \|f\|^2 - \sum_{k=1}^n |\langle f, B_k \rangle|^2,$$

which implies the Bessel-type inequality

$$\sum_{k=1}^{\infty} |\langle f, B_k \rangle|^2 \leq \|f\|^2.$$

Theorem 3.2

Let \mathcal{H} be a complex Hilbert space with a dictionary \mathcal{A} . For any $f \in \mathcal{H}$, with a sequence of consecutively selected a_1, \dots, a_n, \dots from \mathcal{A} under the Pre-orthogonal ρ -Maximal Selection Principle, we have

$$f = \sum_{k=1}^{\infty} \langle f, B_k \rangle B_k,$$

where for each k , the system $\{B_1, \dots, B_k\}$ is the result of the G-S orthonormalization process applied to $\{a_1, \dots, a_k\}$.

The proof provided in the succeeding text directly depends on the Pre-orthogonal ρ -Maximal Selection Principle.

Proof

We prove the theorem by contradiction. Assume that $f = \sum_{k=1}^{\infty} \langle f, B_k \rangle B_k + h$, $h \neq 0, h \perp \overline{\text{span} \mathcal{B}}$, where $\mathcal{B} = \text{span}\{a_1, \dots, a_n, \dots\}$. Because $\overline{\text{span} \mathcal{A}} = \mathcal{H}$, there exists $b \in \mathcal{A}$ such that $\langle h, e_b \rangle \neq 0$. Denote $\mathcal{B}^b = \{b, a_1, \dots, a_n, \dots\}$. Obviously, $h/\text{span} \mathcal{B}^b \neq 0$. Let $\|h/\text{span} \mathcal{B}^b\| = \delta (> 0)$. Denote $\mathcal{B}_n = \{a_1, \dots, a_n\}, \mathcal{B}_{n+1}^b = \{b, a_1, \dots, a_n\}$. We have, by similar reasoning as before,

$$\lim_{n \rightarrow \infty} h/\text{span} \mathcal{B}_{n+1}^b = h/\overline{\text{span} \mathcal{B}^b}.$$

Fix N large enough so that

$$\|h/\text{span} \mathcal{B}_{n+1}^b\| > \delta/2, \quad \text{and} \quad \left\| \sum_{k=N+1}^{\infty} \langle f, B_k \rangle B_k \right\| < \delta/2^m,$$

where m will be determined later. Now, write

$$\begin{aligned} f &= \sum_{k=1}^N \cdot + \sum_{k=N+1}^{\infty} \cdot + h \\ &= \sum_{k=1}^N \cdot + g_{N+1}. \end{aligned}$$

□

On one hand, due to the orthogonality,

$$\begin{aligned} |\langle f, B_{N+1} \rangle| &= |\langle g_{N+1}, B_{N+1} \rangle| \\ &= \left| \left\langle \sum_{k=N+1}^{\infty} \cdot, B_{N+1} \right\rangle \right| \\ &\leq \left\| \sum_{k=N+1}^{\infty} \cdot \right\| \\ &\leq \delta/2^m. \end{aligned}$$

On the other hand, because $\{B_1, \dots, B_N, B_{N+1}^b\}$ is the orthogonalization of $\{a_1, \dots, a_N, b\}$, we have

$$\begin{aligned} |\langle f, B_{N+1}^b \rangle| &= |\langle g_{N+1}, B_{N+1}^b \rangle| \\ &= |\langle h + \sum_{N+1}^{\infty} \cdot, B_{N+1}^b \rangle| \\ &\geq |\langle h, B_{N+1}^b \rangle| - |\langle \sum_{N+1}^{\infty} \cdot, B_{N+1}^b \rangle| \\ &= \|h / \text{span} B_{N+1}^b\| - |\langle \sum_{N+1}^{\infty} \cdot, B_{N+1}^b \rangle| \\ &\geq \delta/2 - \delta/2^m \\ &= \frac{(2^{m-1} - 1)\delta}{2^m}. \end{aligned}$$

Therefore,

$$|\langle f, B_{N+1} \rangle| / \sup\{|\langle f, B_{N+1}^a \rangle| : a \in \mathcal{A}\} < \frac{1}{2^{m-1} - 1}.$$

Now choosing m so large that $\frac{1}{2^{m-1} - 1} < \rho$, we arrive at a contradiction. The proof is complete.

To obtain the convergence rate estimation, we first give some remarks. Assume that we have $\{B_1, \dots, B_{n-1}\}$ as the orthogonalization of $\{a_1, \dots, a_{n-1}\}$. When we have the next element a_n to be added to, and to be made orthogonal with the former B_1, \dots, B_{n-1} , what we do is to expand a_n into the linear expansion $\sum_{k=1}^{n-1} \langle a_n, B_k \rangle B_k$, and then find the n th orthogonal standard remainder $a_n - \sum_{k=1}^{n-1} \langle a_n, B_k \rangle B_k$ given by (3.23). This process gives the projection of a_n into the orthogonal complement space of the linear space $\text{span}\{a_1, \dots, a_{n-1}\}$. We denote such projection operator by $Q_{\{a_1, \dots, a_{n-1}\}}$. That is,

$$Q_{\{a_1, \dots, a_{n-1}\}}(a_n) = a_n - \sum_{k=1}^{n-1} \langle a_n, B_k \rangle B_k, \quad B_n = \frac{Q_{\{a_1, \dots, a_{n-1}\}}(a_n)}{\|Q_{\{a_1, \dots, a_{n-1}\}}(a_n)\|}.$$

In the succeeding text, we will sometimes abbreviate $Q_{\{a_1, \dots, a_{n-1}\}}$ as Q_{n-1} .

On the other hand, we also have

$$g_n = Q_{\{a_1, \dots, a_{n-1}\}}(f), \tag{3.26}$$

where g_n is the n th orthogonal standard remainder of f with respect to the orthonormal system $\{B_1, \dots, B_{n-1}\}$ defined by (3.23). The relation we want to cite is that for any two functions f and g in the complex Hilbert space, we have $\langle f, Q_{\{a_1, \dots, a_{n-1}\}}(g) \rangle = \langle Q_{\{a_1, \dots, a_{n-1}\}}(f), g \rangle$ due to the fact that both the left and right hands are identical with $\langle f, g \rangle - \sum_{k=1}^{n-1} \langle f, B_k \rangle \langle B_k, g \rangle$.

By the just mentioned property of the projection operator, when $\|Q_{\{a_1, \dots, a_{n-1}\}}(a)\| \neq 0$, we have

$$\begin{aligned} |\langle g_n, B_n^a \rangle| &= \frac{1}{\|Q_{\{a_1, \dots, a_{n-1}\}}(a)\|} |\langle Q_{\{a_1, \dots, a_{n-1}\}}(f), Q_{\{a_1, \dots, a_{n-1}\}}(a) \rangle| \\ &= \frac{1}{\|Q_{\{a_1, \dots, a_{n-1}\}}(a)\|} |\langle Q_{\{a_1, \dots, a_{n-1}\}}^2(f), a \rangle| \\ &= \frac{1}{\|Q_{\{a_1, \dots, a_{n-1}\}}(a)\|} |\langle Q_{\{a_1, \dots, a_{n-1}\}}(f), a \rangle| \\ &= \frac{1}{\|Q_{\{a_1, \dots, a_{n-1}\}}(a)\|} |\langle g_n, a \rangle|. \end{aligned} \tag{3.27}$$

Set, for any a_1, \dots, a_{n-1} in \mathcal{A} , and any $a \in \mathcal{A}$,

$$r_n(a) = \|Q_{\{a_1, \dots, a_{n-1}\}}(a)\|. \tag{3.28}$$

We have $r_n(a) \leq 1$. The case $r_n(a) = 1$ is exactly when a is orthogonal with $\text{span}\{a_1, \dots, a_{n-1}\}$. The case $r_n(a) = 0$ is exactly when $a \in \text{span}\{a_1, \dots, a_{n-1}\}$. Weak Orthogonal ρ -Maximal Selection Principle, however, does not allow such selection. Therefore, for the allowed cases, there always

$$|\langle g_n, B_n^a \rangle| = \frac{1}{r_n(a)} |\langle g_n, a \rangle| \geq |\langle g_n, a \rangle|.$$

Now, as in [33] (also see [2]), we introduce

$$H^2(\mathcal{A}, M) = \{f \in H^2 : f = \sum_{k=1}^{\infty} c_k a_k, \sum_{k=1}^{\infty} |c_k| \leq M\}.$$

We have the following:

Theorem 3.3

Let $f \in H^2(\mathcal{A}, M)$. Denote by g_m the orthogonal standard remainder of f with respect to the orthogonalization $\{B_1, \dots, B_{m-1}\}$ of the consecutive selected $\{a_1, \dots, a_{m-1}\}$ under the Pre-orthogonal ρ -Maximal Selection Principle. With $R_m = \max\{r_1, \dots, r_m\}$, $r_n = \sup_k \{r_n(b_k)\}$, where $r_n(b_k)$, depending on a_1, \dots, a_{n-1} and b_k , is defined as in (3.28), we have

$$\|g_m\| \leq \frac{R_m M}{\rho} \frac{1}{\sqrt{m}}.$$

We also need the following result [33]

Lemma 3.4

Let $\{d_n\}_{n=1}^m$ be an m -tuple of non-negative numbers satisfying

$$d_1 \leq A_m, \quad d_{n+1} \leq d_n \left(1 - \frac{d_n}{A_m}\right).$$

Then there holds

$$d_m \leq \frac{A_m}{m}.$$

When the aforementioned relations hold for all integers m and all $n \leq m$, and $A_m \leq A$, then we have, for all m ,

$$d_m \leq \frac{A}{m}.$$

Proof of Theorem 3.3

Assume that $f = \sum_k c_k b_k$ with $\sum_k |c_k| \leq M$. We first note that

$$\|g_{m+1}\|^2 = \|g_m\|^2 - |\langle g_m, B_m \rangle|^2.$$

Next, we have a chain of equality and inequality relations: For each $n \leq m$,

$$\begin{aligned} |\langle g_n, B_n \rangle| &\geq \rho \sup_{a \in \mathcal{A}} |\langle g_n, B_n^a \rangle| \\ &\geq \rho \sup_k |\langle g_n, B_n^{b_k} \rangle| \\ &= \rho \sup_k \frac{|\langle g_n, b_k \rangle|}{r_n(b_k)} \\ &\geq \frac{\rho}{r_n} \sup_k |\langle g_n, b_k \rangle| \\ &\geq \frac{\rho}{r_n M} |\langle g_n, \sum_k c_k b_k \rangle| \\ &= \frac{\rho}{r_n M} |\langle g_n, f \rangle| \\ &\geq \frac{\rho}{R_m M} \|g_n\|^2. \end{aligned}$$

Therefore,

$$\|g_{n+1}\|^2 \leq \|g_n\|^2 \left(1 - \left(\frac{\rho}{R_m M}\right)^2 \|g_n\|^2\right), \quad n \leq m.$$

By invoking Lemma 3.4, we obtain the desired estimate. The proof is complete. □

Comparing the convergence rate of WOGA [30, 33] with that of WP-OGA given in Theorem 3.3, the latter has an extra factor Rm . For small m , the number R_m should be much less than 1. Moreover, at each step of selection, if the candidates for a_n are multiple, we should select one of those giving rise to the smallest $r_n(a_n)$, $n \leq m$, and thus the smallest R_m too. Under such strategy, WP-OGA (P-OGA) is anticipated to achieve considerably better approximation than WOGA (OGA).

4. Complete Dictionary Induced by P-OGA

In this section, we will concentrate in a further study on P-OGA. In an OGA, repeated selections of dictionary elements are excluded by its maximal principle. In contrast, a P-OGA with a dictionary \mathcal{A} whose elements are smoothly parameterized often induces an enlarged dictionary, call *Induced Complete Dictionary*, or *Complete Dictionary* in short, denoted by $\tilde{\mathcal{A}}$. The Maximal Selection Principle of such P-OGA should, in fact, be with respect to the Complete Dictionary $\tilde{\mathcal{A}}$ but not \mathcal{A} (see Theorem 4.1 in the succeeding text). The formulation of $\tilde{\mathcal{A}}$ is described as follows.

Now, assume that elements of the dictionary \mathcal{A} are smoothly parameterized by an m -dimensional complex vector $T = (t^1, \dots, t^m)$ in some open set $\Omega \subset \mathbb{C}^m, m \geq 1$. In P-OGA, at each step, one encounters the following circumstance: One already has a finite orthonormal system $\{B_1, \dots, B_{n-1}\}$ being the G-S orthonormalization of the $(n - 1)$ -tuple $\{a_{T_1}, \dots, a_{T_{n-1}}\}$. Now with an orthogonal remainder g_n , one needs to further select a dictionary element $\tilde{a} = a_{T_n}$ such that the largest possible $|\langle g_n, B_n^{\tilde{a}} \rangle|$ is attainable:

$$|\langle g_n, B_n^{\tilde{a}} \rangle| = \max\{|\langle g_n, B_n^a \rangle| : a \in \mathcal{A}\}, \tag{4.29}$$

where for any $a \in \mathcal{A}$, the function B_n^a is defined through the requirement that the finite system $\{B_1, \dots, B_{n-1}, B_n^a\}$ is the G-S orthonormalization of $\{a_{T_1}, \dots, a_{T_{n-1}}, a\}$. If such \tilde{a} exists, then we are done. The point is that such element \tilde{a} may not exist in \mathcal{A} . We show that under some circumstance, it exists in an enlarged dictionary, called the Induced Complete Dictionary, denoted by $\tilde{\mathcal{A}}$. From now on, we assume that there does not exist $\tilde{a} \in \mathcal{A}$ that makes (4.29) to hold. In case, due to the boundedness $|\langle g_n, B_n^{\tilde{a}} \rangle| \leq \|g_n\|$, there exists a sequence $T^{(k)}$ converging to a boundary point of Ω (including ∞) or an interior point $T_n \in \Omega$ such that

$$\lim_{k \rightarrow \infty} |\langle g_n, B_n^{a_{T^{(k)}}} \rangle| \rightarrow \sup\{|\langle g_n, B_n^a \rangle| : a \in \mathcal{A}\}. \tag{4.30}$$

We note that for each k the point $a_{T^{(k)}}$ must not be in the linear span of $a_{T_1}, \dots, a_{T_{n-1}}$. If it were, then

$$Q_n(a_{T^{(k)}}) = 0,$$

and hence, the new orthonormal function $B_n^{a_{T^{(k)}}}$ cannot be formulated, and there is no further energy gain from $|\langle g_n, B_n^{a_{T^{(k)}}} \rangle|$.

In the classical cases, including the Szegő Dictionary and the Product-Szegő Dictionaries associated with, respectively, the Hardy space in the disc \mathbf{D}^1 and one in the poly-disc \mathbf{D}^2 (Theorem 3.1), when $a_{T^{(k)}}$ tends to the boundary of Ω , there holds

$$\lim_{k \rightarrow \infty} |\langle g_n, B_n^{a_{T^{(k)}}} \rangle| \rightarrow 0. \tag{4.31}$$

In the Clifford algebra and the quaternionic cases, we observe the same phenomenon [27, 28]. In such cases, one concludes that the limit point T_n of $T^{(k)}$ with the property (4.30) must be an interior point of Ω . We show that $a(T_n)$ must be in $\text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}$. In fact, if not, then we can take $\tilde{a} = a(T_n)$ and (4.29) holds, being contrary with our assumption. From now on, we are based on $a_{T_n} \in \text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}$. We show that in the case the limit procedure induces a new system function $B_n^{(\partial_v a_T)(T_n)}$ such that $\{B_1, \dots, B_{n-1}, B_n^{(\partial_v a_T)(T_n)}\}$ is the orthogonalization of $\{a_{T_1}, \dots, a_{T_{n-1}}, (\partial_v a_T)(T_n)\}$, where ∂_v is the directional derivative along some direction $v, \|v\| = 1, \partial_v = v_1 \partial_{t^1} + \dots + v_m \partial_{t^m}, v = (v_1, \dots, v_m), \partial_{t^k} = \frac{1}{2}(\partial_{x_k} - i \partial_{y_k}), t^k = x_k + iy_k, k = 1, \dots, m$. The assertion is proved through the the limit process

$$\begin{aligned} & \lim_{a_{T^{(k)}} \notin \text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}, T^{(k)} \rightarrow T_n} B_n^{a_{T^{(k)}}} \\ &= \lim_{a_{T^{(k)}} \notin \text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}, T^{(k)} \rightarrow T_n} \frac{a_{T^{(k)}} - \sum_{k=1}^{n-1} \langle a_{T^{(k)}}, B_k \rangle B_k}{\|a_{T^{(k)}} - \sum_{k=1}^{n-1} \langle a_{T^{(k)}}, B_k \rangle B_k\|} \\ &= \lim_{a_{T^{(k)}} \notin \text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}, T^{(k)} \rightarrow T_n} \frac{(a_{T^{(k)}} - \sum_{k=1}^{n-1} \langle a_{T^{(k)}}, B_k \rangle B_k) - (a_{T_n} - \sum_{k=1}^{n-1} \langle a_{T_n}, B_k \rangle B_k)}{\|(a_{T^{(k)}} - \sum_{k=1}^{n-1} \langle a_{T^{(k)}}, B_k \rangle B_k) - (a_{T_n} - \sum_{k=1}^{n-1} \langle a_{T_n}, B_k \rangle B_k)\|} \\ &= \lim_{a_{T^{(k)}} \notin \text{span}\{a_{T_1}, \dots, a_{T_{n-1}}\}, T^{(k)} \rightarrow T_n} \frac{(a_{T^{(k)}} - a_{T_n}) / \|T^{(k)} - T_n\| - \sum_{k=1}^{n-1} \langle (a_{T^{(k)}} - a_{T_n}) / \|T^{(k)} - T_n\|, B_k \rangle B_k}{\|(a_{T^{(k)}} - a_{T_n}) / \|T^{(k)} - T_n\| - \sum_{k=1}^{n-1} \langle (a_{T^{(k)}} - a_{T_n}) / \|T^{(k)} - T_n\|, B_k \rangle B_k} \\ &= \frac{(\partial_v a_T)(T_n) - \sum_{k=1}^{n-1} \langle (\partial_v a_T)(T_n), B_k \rangle B_k}{\|(\partial_v a_T)(T_n) - \sum_{k=1}^{n-1} \langle (\partial_v a_T)(T_n), B_k \rangle B_k\|}, \end{aligned}$$

where v is the tangential direction of the passage $T^{(k)} \rightarrow T_n$. We note that since T_n is an interior point of Ω we can always choose a sequence of points $T^{(k)}$ tending to T_n along an axis direction. Thus in the above argument the term directional derivative can be replaced by partial derivative.

If the parameter space is \mathbb{C} , the aforementioned directional derivative or partial derivative reduces to the standard complex derivative, and likewise in the Clifford and quaternionic cases.

Denote by $\mathcal{A}_k, k = 1, 2, \dots$, the function set consisting of all possible normalized directional partial derivatives of the functions in \mathcal{A}_{k-1} , where $\mathcal{A}_0 = \mathcal{A}$. Note that for each k, \mathcal{A}_k is smoothly parameterized by the same parameters T in \mathbb{C}^m .

Definition 1 (Induced Complete Dictionary)

Let \mathcal{H} be a complex Hilbert space and \mathcal{A} a dictionary of \mathcal{H} . Denote by

$$\tilde{\mathcal{A}} = \cup_{k=0}^{\infty} \mathcal{A}_k$$

the Complete Dictionary Induced from \mathcal{A} .

Examples of such formulated complete dictionaries include the Complete Szegő Dictionary $\tilde{\mathcal{D}}$ given in Section 1 (also see [1]), where directional derivatives are replaced by the complex derivative, and one in [27] for the quaternions case. We note that in the 1-D AFD case, the orthonormal system functions B_n 's, no matter with repeated parameters or not, have an explicit and uniform formula in the parameters: The multiple indicates the order of the derivative. Because of the aforementioned analysis, from now on, to perform P-OGA, we will be basing on the complete dictionary $\tilde{\mathcal{A}}$ consisting of the elements of \mathcal{A} , as well as all possible first and higher-order directional derivatives.

Now, we show that P-OGA is applicable for the poly-disc Hardy H^2 space with the Complete Product-Szegő Dictionary. We have the following:

Theorem 4.1

For the poly-disc Hardy H^2 space with the Complete Product-Szegő Dictionary $\tilde{\mathcal{D}}^2$, we can take $\rho = 1$ in the Pre-orthogonal ρ -Maximal Selection Principle (3.24).

Proof

Denote by $E_{\{a,b\}}$ a general element of $\tilde{\mathcal{D}}^2$. They are parameterized by complex pairs (a, b) in \mathbf{D}^2 . The elements in $\tilde{\mathcal{D}}^2 \setminus \mathcal{D}^2$ are not of the tensor product form, they, however, are finite linear combinations of tensor products of the form

$$N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b, \quad k + l > 0, \tag{4.32}$$

where $N(a, k)$ and $N(b, l)$ are the normalizing constants such that

$$\|N(a, k) \partial_a^k e_a\| = 1, \quad \|N(b, l) \partial_b^l e_b\| = 1. \tag{4.33}$$

□

Note that $N(a, 0) = \sqrt{1 - |a|^2}$, $N(b, 0) = \sqrt{1 - |b|^2}$. Because of the singularity of $\partial_a^k e_a$ when $|a| \rightarrow 1$ and that of $\partial_b^l e_b$ when $|b| \rightarrow 1$, we have

$$\lim_{|a| \rightarrow 1} N(a, k) = 0, \quad \lim_{|b| \rightarrow 1} N(b, l) = 0, \quad k, l \geq 0. \tag{4.33}$$

It amounts to show that there exists an interior pair $(a_n, b_n) \in \mathbf{D}^2$ such that

$$(a_n, b_n) = \operatorname{argmax}\{|\langle g_n, \tilde{B}_n \rangle| : (a, b) \in \mathbf{D}^2, \{B_1, \dots, B_{n-1}, \tilde{B}_n\} \text{ is the G-S orthogonalization of } E_{\{a_1, b_1\}}, \dots, E_{\{a_{n-1}, b_{n-1}\}}, E_{\{a, b\}}\}, \tag{4.34}$$

where $a_1, b_1, \dots, a_{n-1}, b_{n-1}$ are previously fixed. The $E_{\{a_n, b_n\}}$ will be the next selected element in the Complete Product-Szegő Dictionary $\tilde{\mathcal{D}}^2$ so to formulate B_n . To prove the availability of (4.34), we first show

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} |\langle g_n, \tilde{B}_n \rangle| = 0. \tag{4.35}$$

Owing to the general relation (3.27) proved for $a \in \tilde{\mathcal{D}}^2$ and the remark on the formulation of $E_{\{a,b\}}$, the aforementioned limit is a consequence of

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} |\langle g_n, N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \rangle| = 0 \tag{4.36}$$

and

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} \|Q_{n-1}(\partial_{N(a,k)a}^k e_a \otimes N(b, l) \partial_b^l e_b)\| = 1, \tag{4.37}$$

where $k + l \geq 0$.

Because of the orthogonality between

$$N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \quad \text{and} \quad g - \langle g, N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \rangle N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b,$$

we have

$$\|g_n\|^2 = |\langle g_n, N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \rangle|^2 + \|g - \langle g, N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \rangle N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b\|^2.$$

Then (4.36) is a consequence of

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} \|g - \langle g, N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \rangle N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b\|^2 = 0. \quad (4.38)$$

Performing what is carried out in (3.22), we are reduced to showing

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} \|(P_r \otimes P_s) * (N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b)\| \rightarrow 0. \quad (4.39)$$

Now, with the fixed $0 < r < 1$ and $0 < s < 1$, because $N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b \in H^2$, there follows, for $z = re^{it}$, $w = se^{iu}$,

$$(P_r \otimes P_s) * (N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b)(e^{it}, e^{iu}) = (N(a, k) \partial_a^k e_a)(z)(N(b, l) \partial_b^l e_b)(w).$$

With explicit computation, we have

$$\|(P_r \otimes P_s) * (N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b)\|^2 = \frac{N(a, k)}{N(ra, k)} \frac{N(b, l)}{N(sb, l)} \rightarrow 0, \text{ as } |a| \rightarrow 1 \text{ or } |b| \rightarrow 1.$$

With the relation (3.26), the same reasoning gives

$$1 = \|N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b\|^2 = \sum_{k=1}^{n-1} \left\| \left\langle N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b, B_k \right\rangle \right\|^2 + \|Q_{n-1} (N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b)\|^2.$$

By invoking (4.36),

$$\lim_{|a| \rightarrow 1 \text{ or } |b| \rightarrow 1} \sum_{k=1}^{n-1} \left\| \left\langle N(a, k) \partial_a^k e_a \otimes N(b, l) \partial_b^l e_b, B_k \right\rangle \right\|^2 = 0.$$

We hence obtain (4.37). Therefore, we have proven (4.35). Next, we indicate that we can always select an element of $\widetilde{\mathcal{D}}^2$, being a linear combination of finitely many directional derivatives of certain orders of the elements in \mathcal{D}^2 , that gives rise to the maximum of $|\langle g_n, B_n^a \rangle|$, $a \in \widetilde{\mathcal{A}}$ (see the explanation before the definition of Induced Complete Dictionary). The proof is complete.

The following theorem shows that in the one complex unit disc case, the Complete Szegő Dictionary defined in Section 1 through (1.3) coincides with the Complete Dictionary Induced by the Szegő Dictionary defined in Section 4, and under which the related P-OGA reduces to 1-D AFD.

Theorem 4.2

In the 1-D unit disc context, the P-OGA under the Complete Szegő Dictionary $\widetilde{\mathcal{D}}$ reduces to AFD.

Proof

In view of the relation

$$\langle f_k, e_{a_k} \rangle = \langle g_k, B_k \rangle$$

cited in (1.9), the AFD selection of e_{a_k} in \mathcal{D} in relation to the reduced remainder f_k corresponds to the P-OGA selection of B_k in relation to the orthogonal standard remainder g_k . As indicated in Section 1 (Remark 4), the system functions B_k are formed through the G-S orthogonalization on elements in Complete Szegő Dictionary; we see that the P-OGA, in fact, is performed with respect to the Complete Szegő Dictionary $\widetilde{\mathcal{D}}$. We note that a system function $B_k = B_{\{a_1, \dots, a_n\}}$ is parameterized directly by $\mathbf{a} = \{a_1, \dots, a_n\} \in \cup_{k=1}^{\infty} \mathbf{D}^k$, where the multiple m_k of a_k , $1 \leq k \leq n$, indicates the order of the derivative of the Szegő kernel in use (see the definition of $E_k(z)$ in Section 1). The proof is complete. \square

We finally note that all the results obtained in Sections 2 and 3 for product spaces from several copies of the unit disc \mathbf{D} have their counterparts in product spaces from several copies of the upper-half complex plane.

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